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APA Abstract Interpretation

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1. Abstract interpretation



Abstract Interpretation
=
analysis as a **simplification** of **running** a computer program.



- ▶ During program execution we compute the values of variables.
 - ▶ And our location in the program.
- ▶ During abstract interpretation we might
 - ▶ compute only the signs of integer variables,
 - ▶ compute where closures are created, but not the closures themselves,
 - ▶ compute only the lengths of lists,
 - ▶ compute only the types of variables.
- ▶ Typically, but not necessarily, we compute this for any given location.
- ▶ The right simplification depends on the analysis we are attempting.



- ▶ For certain “good” abstract interpretations, soundness of the analysis follows “immediately” from the soundness of the semantics of the language.
- ▶ The latter needs to be proved only **once**, but **many** analyses may benefit.
- ▶ Semantics must be formally defined.
 - ▶ E.g., operational semantics, i.e., specification of interpreter
- ▶ Since static analyses must be sound for **all executions**, we need a **collecting semantics** for the language.
- ▶ Abstracting to a complete lattice with ACC gives guarantee of termination.



- ▶ An interpreter keeps track of the state of the program.
- ▶ Usually it contains:
 - ▶ What program point are we at?
 - ▶ For every variable, what value does it currently have?
 - ▶ What does the stack look like?
 - ▶ What is allocated on the heap?



- ▶ For an imperative languages (**While**) without procedures we track only the program point and the variables to value mapping.
- ▶ To deal with procedures, also track the stack.
- ▶ The state is determined by the language constructs we support.
 - ▶ Adding **new** implies the need to keep track of the heap.
- ▶ For the moment, we assume

$$\mathbf{State} = \mathbf{Lab} \times (\mathbf{Var} \rightarrow \mathbf{Data})$$

where **Data** typically contains integers, reals and booleans.



- ▶ In abstract interpretation we simplify the state.
- ▶ And operations on the state should behave consistently with the abstraction.
- ▶ What if the state is already so information poor that the information we want is not in the state to begin with?
- ▶ Our state

$$\text{State} = \text{Lab} \times (\text{Var} \rightarrow \text{Data})$$

has only momentaneous information:

- ▶ It does not record dynamic information for the program, e.g., executions.



- ▶ Many program analyses concern dynamic properties.
- ▶ Examples:
 - ▶ Record the minimum and maximum value an integer identifier may take.
 - ▶ In a dynamically typed language: compute all types a variable may have.
 - ▶ Record all the function abstractions an identifier might evaluate to.
 - ▶ Record the set of pairs (x, ℓ) in case x may have gotten its last value at program point ℓ .
- ▶ We must first enrich the state to hold this information.



- ▶ Static analysis results should hold for *all* runs.
- ▶ Code is only dead if all executions avoid it.
- ▶ An interpreter considers only a single execution at the time.
- ▶ Redefine semantics to specify all executions “in parallel”.
- ▶ This is called a **collecting semantics**.
- ▶ Static analysis is on a simplified version (abstraction) of the collecting semantics.
 - ▶ Because, usually, the collecting semantics is very infinite.



- ▶ A collecting semantics for `While` might record sets of execution histories:

$$\mathbf{State} = \mathcal{P}([\mathbf{Lab}, \text{Maybe}(\mathbf{Var}, \mathbf{Data})])$$

- ▶ Example: `if [x > 0]1 then [y := -3]2 else [skip]3`
- ▶ $\{[(?, \text{Just } (x, 0)), (? , \text{Just } (y, 0)), (1, \text{Nothing}), (3, \text{Nothing})], [(?, \text{Just } (x, 2)), (? , \text{Just } (y, 0)), (1, \text{Nothing}), (2, \text{Just } (y, -3))]\}$



- ▶ Consider **State** = **Lab** \rightarrow $\mathcal{P}(\mathbf{Var} \rightarrow \mathbf{Data})$.
 - ▶ Sets of functions telling us what values variables can have right before a given program point.
- ▶ We repeat: `if [x > 0]1 then [y := -3]2 else [skip]3`
- ▶ For the above program we have (given the initial values):
 - $1 \mapsto \{[x \mapsto 0, y \mapsto 0], [x \mapsto 2, y \mapsto 0]\}$,
 - $2 \mapsto \{[x \mapsto 2, y \mapsto 0]\}$, $3 \mapsto \{[x \mapsto 0, y \mapsto 0]\}$
- ▶ At the end of the program, we have
 - $\{[x \mapsto 2, y \mapsto -3], [x \mapsto 0, y \mapsto 0]\}$
- ▶ The semantics does not record that $[x \mapsto 2, y \mapsto 0]$ leads to $[x \mapsto 2, y \mapsto -3]$.



- ▶ Also track the heap and/or stack (if the language needs it).
- ▶ In an **instrumented semantics** information is stored that does not influence the outcome of the execution.
 - ▶ For example, timing information.
- ▶ Choose one which is general enough to accommodate all your analyses.
 - ▶ You cannot analyze computation times if there is no information about it in your collecting semantics



- ▶ We cannot compute all the states for an arbitrary program: it might take an infinite amount of time and space.
- ▶ We now must simplify the semantics.
- ▶ How far?
 - ▶ Trade-off between resources and amount of detail.
- ▶ The least one can demand is that analysis time is finite.
- ▶ In some cases, we have to give up more detail than we can allow.
 - ▶ Therefore: widening



- ▶ We take $\mathcal{P}(\mathbf{Var} \rightarrow \mathbf{Data})$ as a starting point.
- ▶ Example: $S = \{[x \mapsto 2, y \mapsto 0], [x \mapsto -2, y \mapsto 0]\}$
- ▶ Abstract to $\mathbf{Var} \rightarrow \mathcal{P}(\mathbf{Data})$ (relational to independent):
 - ▶ S now becomes $[x \mapsto \{-2, 2\}, y \mapsto \{0\}]$.
- ▶ Abstract further to intervals $[x, y]$ for $x \leq y$:
 - ▶ S now becomes represented by $[x \mapsto [-2, 2], y \mapsto [0, 0]]$
- ▶ Abstract further to $\mathbf{Var} \rightarrow \mathcal{P}(\{0, -, +\})$:
 - ▶ S now becomes $[x \mapsto \{-, 0, +\}, y \mapsto \{0\}]$.
- ▶ Mappings are generally not injective:
 $\{[x \mapsto 2, y \mapsto 0], [x \mapsto -2, y \mapsto 0], [x \mapsto 0, y \mapsto 0]\}$ also maps to $[x \mapsto \{-, 0, +\}, y \mapsto \{0\}]$.



- ▶ Consider: you have an interpreter for your language.
- ▶ It knows how to add integers, but not how to add signs.
- ▶ Would be great if the operators followed immediately from the abstraction.
- ▶ This is the case, but the method is not constructive:
 - ▶ How to (effectively) compute $\{-\} +_S \{-\}$ in terms of $+$ for integers?
- ▶ It does give a correctness criterion for the abstracted operators: the result of $\{-\} +_S \{-\}$ **must** include $-$.



- ▶ Consider abstraction from

$$\mathbf{Lab} \rightarrow \mathcal{P}(\mathbf{Var} \rightarrow \mathbf{Z})$$

to

$$\mathbf{Lab} \rightarrow \mathbf{Var} \rightarrow \mathcal{P}(\{0, -, +\}) .$$

- ▶ When we add integers, the result is deterministic: two integers go in, one comes out.
- ▶ If we add signs $+$ and $-$, then we must get $\{+, 0, -\}$.
- ▶ The abstract add is **non-deterministic**.
- ▶ Another reason for working with **sets** of abstractions of integers.
 - ▶ We already needed those to deal with sets of executions.



- ▶ Practically, Abstract Interpretation concerns itself with the “right” choice of lattice, and how to compute safely with its elements.
- ▶ Assume semantics is $L = \mathbf{Lab}_* \rightarrow \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$ where \sqsubseteq is elementwise \subseteq .
 - ▶ Forms a complete lattice, but does not satisfy ACC!
- ▶ For Constant Propagation, abstract L to

$$M = \mathbf{Lab}_* \rightarrow (\mathbf{Var}_* \rightarrow \mathbf{Z}^\top)_\perp \text{ with } \mathbf{Z}^\top = \mathbf{Z} \cup \{\top\} .$$

- ▶ M does have ACC.



- ▶ Recall:

$$L = \mathbf{Lab}_* \rightarrow \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$$

$$M = \mathbf{Lab}_* \rightarrow (\mathbf{Var}_* \rightarrow \mathbf{Z}^\top)_\perp \text{ with } \mathbf{Z}^\top = \mathbf{Z} \cup \{\top\}$$

- ▶ For each label, $\alpha : L \rightarrow M$ maps \emptyset to \perp , collects all values for a given variable together in a set and then maps $\{i\}$ to i and others to \top .
- ▶ Example:

$$\alpha(f) = [1 \mapsto [x \mapsto \top, y \mapsto 0], 2 \mapsto [x \mapsto 8, y \mapsto 1]]$$

$$\text{where } f = [1 \mapsto \{[x \mapsto -8, y \mapsto 0], [x \mapsto 8, y \mapsto 0]\}, \\ 2 \mapsto \{[x \mapsto 8, y \mapsto 1]\}]$$



- ▶ Afterwards, if necessary, transform the solution back to one for L .
- ▶ Transformation by **concretization function** γ from M to L .
- ▶ Let $m = [1 \mapsto [x \mapsto \top, y \mapsto 0], 2 \mapsto [x \mapsto 8, y \mapsto 1]]$.
- ▶ Then $\gamma(m) = [1 \mapsto \{[x \mapsto a, y \mapsto 0] \mid a \in \mathbf{Z}\}, 2 \mapsto \{[x \mapsto 8, y \mapsto 1]\}]$
- ▶ Note: $\gamma(m)$ is infinite!
 - ▶ But the original concrete value was not.
- ▶ If α and γ have certain properties then abstraction may lose precision, but not correctness.



2. Galois Connections and Galois Insertions



- ▶ Not every combination of abstraction and concretization function is “good” .
- ▶ When we abstract, we prefer the soundness of the concrete lattice to be inherited by the abstract one.
 - ▶ In particular, the soundness of an analysis derives from the soundness of the collecting operational semantics.
 - ▶ NB: executing the collecting operational semantics is also a sort of analysis.
- ▶ The Cousots defined when this is the case.
- ▶ These abstractions are termed **Galois Insertions**
 - ▶ Slightly more general, **Galois Connections** aka **adjoints**.
- ▶ Abstraction can be a stepwise process.
- ▶ In the end everything relates back to the soundness of the collecting semantics.



- ▶ Let $L = (\mathcal{P}(\mathbf{Z}), \subseteq)$ and $M = (\mathcal{P}(\{0, +, -\}), \subseteq)$.
- ▶ Let $\alpha : L \rightarrow M$ be the abstraction function defined as

$$\alpha(S) = \{\text{sign}(z) \mid z \in S\} \text{ where}$$

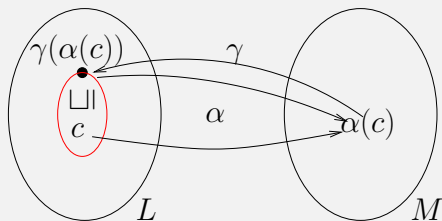
$\text{sign}(x) = 0$ if $x = 0$, $+$ if $x > 0$ and $-$ if $x < 0$.

- ▶ For example: $\alpha(\{0, 2, 20, 204\}) = \{0, +\}$ and $\alpha(O) = \{-, +\}$ where O is the set of odd numbers.
- ▶ Obviously, α is monotone: if $x \subseteq y$ then $\alpha(x) \subseteq \alpha(y)$.



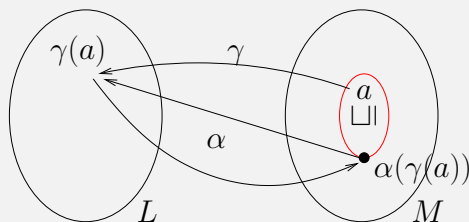
- ▶ Let $L = (\mathcal{P}(\mathbf{Z}), \subseteq)$ and $M = (\mathcal{P}(\{0, +, -\}), \subseteq)$.
- ▶ The concretization function γ is defined by:
$$\begin{aligned}\gamma(T) = & \{1, 2, \dots \mid + \in T\} \\ & \cup \{\dots, -2, -1 \mid - \in T\} \\ & \cup \{0 \mid 0 \in T\}\end{aligned}$$
- ▶ Again, obviously, γ monotone.
- ▶ Monotonicity of α and γ and **two extra demands** make (L, α, γ, M) into a **Galois Connection**.





- ▶ α removes detail, so when going back to L we expect to lose information.
 - ▶ Gaining information would be non-monotone.
- ▶ Demand 1: for all $c \in L$, $c \sqsubseteq_L \gamma(\alpha(c))$
- ▶ For the set O of odd numbers,
 $O \subseteq \gamma(\alpha(O)) = \gamma(\{+, -\}) = \{\dots, -2, -1, 1, 2, \dots\}$
- ▶ What about $\alpha(\gamma(\alpha(c)))$? It equals $\alpha(c)$.





- ▶ Demand 2: for all $a \in M$, $\alpha(\gamma(a)) \sqsubseteq_M a$
- ▶ Dual version of demand 1.
- ▶ Abstracting the concrete value of an abstract values gives a lower bound of the abstract value.
- ▶ For $a = \{+, 0\} \in M$, $\alpha(\gamma(a)) = \alpha(\{0, 1, 2, \dots\}) = \{0, +\}$
- ▶ What about $\gamma(\alpha(\gamma(a)))$? It equals $\gamma(a)$.



- ▶ Sometimes Demand 2 becomes
Demand 2': for all $a \in M$, $\alpha(\gamma(a)) = a$.
- ▶ It is then called a Galois Insertion.
- ▶ Often a Connection is an Insertion, but not always.
- ▶ A Connection can always be made into an Insertion
 - ▶ Remove values from abstract domain that cannot be reached.



- ▶ Consider the complete lattices $L = (\mathcal{P}(\mathbf{Z}), \subseteq)$ and $M = \mathcal{P}(\{0, +, -\} \times \{\text{odd}, \text{even}\}, \dots)$ and the obvious abstraction $\alpha : L \rightarrow M$.
- ▶ Concretization: what is $\gamma(\{(0, \text{odd}), (-, \text{even})\})$?



- ▶ Consider the complete lattices $L = (\mathcal{P}(\mathbf{Z}), \subseteq)$ and $M = \mathcal{P}(\{0, +, -\} \times \{\text{odd}, \text{even}\}, \dots)$ and the obvious abstraction $\alpha : L \rightarrow M$.
- ▶ Concretization: what is $\gamma(\{(0, \text{odd}), (-, \text{even})\})$?
- ▶ What happens to $(0, \text{odd})$? We ignore it!
- ▶ Abstracting back:

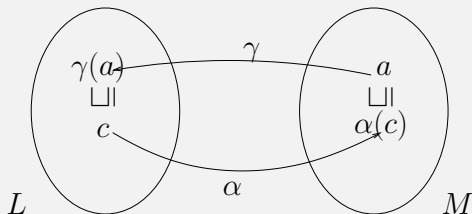
$$\alpha(\gamma(\{(0, \text{odd}), (-, \text{even})\})) \text{ gives } \{(-, \text{even})\}$$

and note that

$$\{(-, \text{even})\} \subset \{(0, \text{odd}), (-, \text{even})\}$$

- ▶ Why be satisfied before you have na Insertion?
 - ▶ The Connection may be much easier to specify.





- ▶ Now α and γ are total functions between L and M .
- ▶ Abstraction of less gives less: $c \sqsubseteq \gamma(a)$ implies $\alpha(c) \sqsubseteq a$.
- ▶ Concretization of more gives more: $\alpha(c) \sqsubseteq a$ implies $c \sqsubseteq \gamma(a)$.
- ▶ Together: (L, α, γ, M) is an **adjoint**.
- ▶ Thm: adjoints are equivalent to Galois Connections.



- ▶ Reachability:

$M = \mathbf{Lab}_* \rightarrow \{\perp, \top\}$ where
 \perp describes “not reachable”,
 \top describes “might be reachable”.

- ▶ Undefined variable analysis:

$M = \mathbf{Var}_* \rightarrow \{\perp, \top\}$ where
 \top describes “might get a value”,
 \perp describes “never gets a value”.

- ▶ Undefined before use analysis:

$M = \mathbf{Lab}_* \rightarrow \mathbf{Var}_* \rightarrow \{\perp, \top\}$



- ▶ Building Galois Connections from smaller ones.
- ▶ Reuse to save on proofs and implementations.
- ▶ Quick look at:
 - ▶ composition of Galois Connections,
 - ▶ total function space,
 - ▶ independent attribute combination,
 - ▶ direct product.



- ▶ Construct a Galois Connection from the collecting semantics

$$L = \mathbf{Lab}_* \rightarrow \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$$

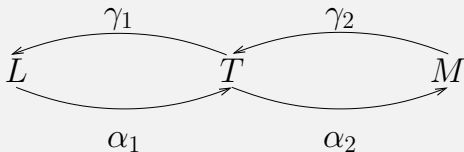
to

$$M = \mathbf{Lab}_* \rightarrow \mathbf{Var}_* \rightarrow \mathbf{Interval}$$

- ▶ M can be used for Array Bound Analysis:
 - ▶ Of interest are only the minimal and maximal values.
- ▶ First we abstract L to $T = \mathbf{Lab}_* \rightarrow \mathbf{Var}_* \rightarrow \mathcal{P}(\mathbf{Z})$, and then T to M .
- ▶ The abstraction α from L to M is the **composition** of these two.
- ▶ The intermediate Galois Connections are built using the **total function space combinator**.



- ▶ The general picture:



- ▶ The composition of the two can be taken directly from the picture:

$$(L, \alpha_2 \circ \alpha_1, \gamma_1 \circ \gamma_2, M) .$$

- ▶ Thm: always a Connection (Insertion) if the two ingredients are Connections (Insertions)



- ▶ $L = \mathbf{Lab}_* \rightarrow \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$ is a **relational** lattice,
 $T = \mathbf{Lab}_* \rightarrow \mathbf{Var}_* \rightarrow \mathcal{P}(\mathbf{Z})$ is only suited for **independent attribute analysis**.
- ▶ This kind of step occurs quite often: define separately for reuse.
- ▶ Example:

$$[1 \mapsto \{[x \mapsto 2, y \mapsto -3], [x \mapsto 0, y \mapsto 0]\}]$$

should abstract to

$$[1 \mapsto [x \mapsto \{0, 2\}, y \mapsto \{-3, 0\}]] .$$



- ▶ We first try to get from
$$L' = \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$$
 to
$$T' = \mathbf{Var}_* \rightarrow \mathcal{P}(\mathbf{Z}).$$
 - ▶ “Add” back the \mathbf{Lab}_* by invoking the total function space combinator.
- ▶ Start by finding a Galois Connection (α'_1, γ'_1) from
$$L' = \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$$
 to $T' = \mathbf{Var}_* \rightarrow \mathcal{P}(\mathbf{Z}).$
- ▶ $\{[x \mapsto 2, y \mapsto -3], [x \mapsto 0, y \mapsto 0]\}$ should abstract to
$$[x \mapsto \{0, 2\}, y \mapsto \{-3, 0\}].$$
- ▶ $\alpha'_1(S) = \lambda v . \{z \mid \exists f \in S . z = f(v)\}$
 - ▶ Collect for each variable v all the values it maps to.



- ▶ $L' = \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$
 $T' = \mathbf{Var}_* \rightarrow \mathcal{P}(\mathbf{Z})$.
- ▶ γ'_1 unfolds sets of values to sets of functions,
 - ▶ simply by taking all combinations.
- ▶ From $[x \mapsto \{0, 2\}, y \mapsto \{-3, 0\}]$ we obtain
 $\{[x \mapsto 2, y \mapsto -3], [x \mapsto 0, y \mapsto 0],$
 $[x \mapsto 2, y \mapsto 0], [x \mapsto 0, y \mapsto -3]\}$



- ▶ Let $(L', \alpha'_1, \gamma'_1, T')$ be the Galois Connection just constructed.
- ▶ How can we obtain a Galois Connection $(L, \alpha_1, \gamma_1, T)$?
 - ▶ Use the **total function space combinator**.
- ▶ For a fixed set, say $S = \mathbf{Lab}_*$, $(L', \alpha'_1, \gamma'_1, T')$ is transformed into a Galois Connection between $L = S \rightarrow L'$ and $T = S \rightarrow T'$.
- ▶ L and T are complete lattices if L' and T' are (App. A).
- ▶ The construction builds α_1 and γ_1 out of α'_1 and γ'_1 .
- ▶ Apply primed versions pointwise:
 - ▶ For each $\phi \in L$: $\alpha_1(\phi) = \alpha'_1 \circ \phi$ (see also p. 96)
 - ▶ Similarly, for each $\psi \in T$: $\gamma_1(\psi) = \gamma'_1 \circ \psi$.



- ▶ What remains is getting from $T = \mathbf{Lab}_* \rightarrow \mathbf{Var}_* \rightarrow \mathcal{P}(\mathbf{Z})$ to $M = \mathbf{Lab}_* \rightarrow \mathbf{Var}_* \rightarrow \mathbf{Interval}$.
- ▶ Intervals: $\perp = [\infty, -\infty]$, $[0, 0]$, $[-\infty, 2]$, $\top = [-\infty, \infty]$.
- ▶ Abstraction from $\mathcal{P}(\mathbf{Z})$ to **Interval**:
 - ▶ if set empty take \perp ,
 - ▶ find minimum and maximum,
 - ▶ if minimum undefined: take $-\infty$,
 - ▶ if maximum undefined: take ∞ .
- ▶ Invoke **total function space combinator** twice to “add” \mathbf{Lab}_* and \mathbf{Var}_* on both sides.

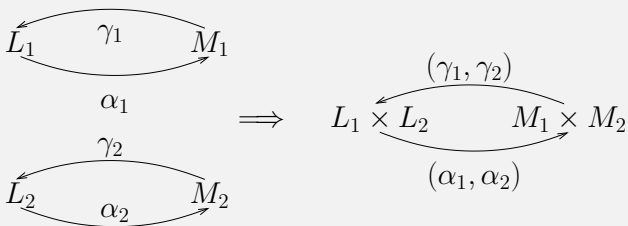


- ▶ Starting from the lattice $\mathcal{P}(\mathbf{Z})$ we can abstract to $M_1 = \mathcal{P}(\{\text{odd}, \text{even}\})$ and $M_2 = \mathcal{P}(\{-, 0, +\})$.
- ▶ Combine the two into one Galois Connection between $L = \mathcal{P}(\mathbf{Z})$ and $M = \mathcal{P}(\{\text{odd}, \text{even}\}) \times \mathcal{P}(\{-, 0, +\})$.
- ▶ Given that we have $(L, \alpha_1, \gamma_1, M_1)$ and $(L, \alpha_2, \gamma_2, M_2)$ we obtain $(L, \alpha, \gamma, M_1 \times M_2)$ where
 - ▶ $\alpha(c) = (\alpha_1(c), \alpha_2(c))$ and
 - ▶ $\gamma(a_1, a_2) = \gamma_1(a_1) \sqcap \gamma_2(a_2)$
- ▶ Why take the meet (greatest lower bound)?



- ▶ Starting from the lattice $\mathcal{P}(\mathbf{Z})$ we can abstract to $M_1 = \mathcal{P}(\{\text{odd}, \text{even}\})$ and $M_2 = \mathcal{P}(\{-, 0, +\})$.
- ▶ Combine the two into one Galois Connection between $L = \mathcal{P}(\mathbf{Z})$ and $M = \mathcal{P}(\{\text{odd}, \text{even}\}) \times \mathcal{P}(\{-, 0, +\})$.
- ▶ Given that we have $(L, \alpha_1, \gamma_1, M_1)$ and $(L, \alpha_2, \gamma_2, M_2)$ we obtain $(L, \alpha, \gamma, M_1 \times M_2)$ where
 - ▶ $\alpha(c) = (\alpha_1(c), \alpha_2(c))$ and
 - ▶ $\gamma(a_1, a_2) = \gamma_1(a_1) \sqcap \gamma_2(a_2)$
- ▶ Why take the meet (greatest lower bound)?
 - ▶ It enables us to ignore combinations (a_1, a_2) that cannot occur.
- ▶ $\gamma(\{\{\text{odd}\}, \{0\}\}) = \gamma_1(\{\text{odd}\}) \cap \gamma_2(\{0\})$
 $= \{\dots, -1, 1, \dots\} \cap \{0\} = \emptyset.$





- ▶ Example: $L_1 = L$ and $M_1 = M$, and M_2 is some abstraction of L_2 which describes the state of the heap at different program points.
- ▶ Define α and γ between $L_1 \times L_2$ and $M_1 \times M_2$ as follows:
 - ▶ $\alpha(c_1, c_2) = (\alpha_1(c_1), \alpha_2(c_2))$
 - ▶ $\gamma(a_1, a_2) = (\gamma_1(a_1), \gamma_2(a_2))$.
- ▶ Abstractions are done independently.



3. Widening



- ▶ We abstracted from $L = \mathbf{Lab}_* \rightarrow \mathcal{P}(\mathbf{Var}_* \rightarrow \mathbf{Z})$ to
 $M = \mathbf{Lab}_* \rightarrow \mathbf{Var}_* \rightarrow \mathbf{Interval}$.
- ▶ M is a prime candidate for Array Bound Analysis:
At every program point, determine the minimum and maximum value for every variable.



- ▶ Consider the program
[x := 0]¹
while [x >= 0]² do
 [x := x + 1]³;
- ▶ The intervals for x in Analysis_o(2) turn out to be

$$[0, 0] \sqsubseteq [0, 1] \sqsubseteq [0, 2] \sqsubseteq [0, 3] \sqsubseteq \dots$$

- ▶ Not having ACC prevents termination.
- ▶ When the loop is bounded (e.g., [x < 10000]²) convergence to [0, 10001] takes a **long** time.



- ▶ Two ways out:
 - ▶ abstract M further to a lattice that does have ACC, or
 - ▶ ensure all infinite chains in M are traversed in finite time.
- ▶ In this case, there does not seem to be any further abstraction possible.
- ▶ So let's consider the second: **widening**.



- ▶ Widening \approx a non-uniform coarsening of the lattice.
- ▶ We promise not to visit some parts of the lattice.
 - ▶ Which parts typically depends on the program.
- ▶ Essentially making larger skips along ascending chains than necessary.
- ▶ This buys us termination.
- ▶ But we pay a price: no guarantee of a **least fixed point**.
 - ▶ By choosing a clever widening we can hope it won't be too bad.



- ▶ Consider the following program:

```
int i, c, n,  
int A[20], C[], B[];  
C = new int[9];  
input n; B = new int[n];  
if (A[i] < B[i]) then  
    C[i/2] = B[i];
```

- ▶ Which bound checks are certain to succeed?
 - ▶ Arrays A and C have static sizes, which can be determined 'easily' (resizing is prohibited).
 - ▶ Therefore: find the possible values of i .
 - ▶ If always $i \in [0, 17]$, then omit checks for A and C .
 - ▶ If always $i \in [0, 19]$, then omit checks for A .
 - ▶ Nothing to be gained for B : it is dynamic.



- ▶ For the arrays **A** and **C**, the fact $i \in [-20, 300]$ is (almost) as bad as $[-\infty, \infty]$.
- ▶ Why then put such large intervals in the lattice?
- ▶ Widening allows us to tune (per program) what intervals are of interest.

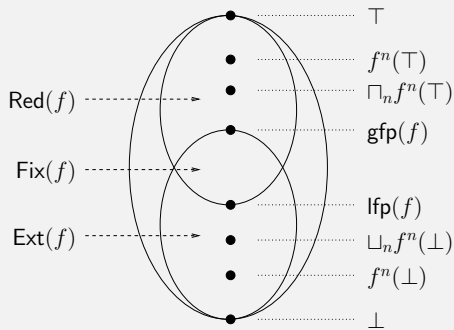


- ▶ Consider, for simplicity, the set of all constants C in a program P .
 - ▶ Includes those that are used to define the sizes of arrays.
- ▶ What if, when we join two intervals, we consider as result only intervals, the boundaries of which consist of values taken from $C \cup \{-\infty, \infty\}$?
- ▶ To keep it safe, every value over $\sup(C)$ must be mapped to ∞ , and below $\inf(C)$ to $-\infty$.
- ▶ A program has only a finite number of constants: number of possible intervals for every program point is now finite.



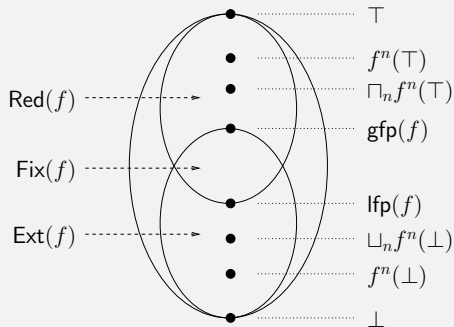
- ▶ Which constants work well depends on how the arrays are addressed: $A[2*i + j] = B[3*i] - C[i]$
- ▶ Variations can be made: take all constants plus or minus one, etc. etc.
- ▶ In a language like Java and C all arrays are zero-indexed
 - ▶ Consider only positive constants ($A[-i]$?).
- ▶ What works well can only be empirically established.





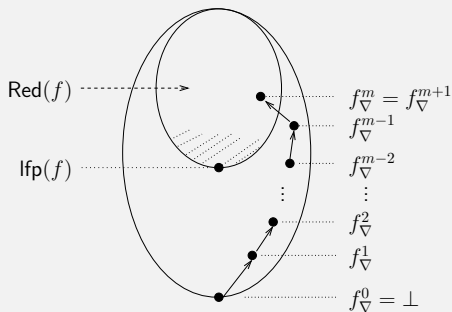
- ▶ $\text{Red}(f) = \{x \mid f(x) \sqsubseteq x\}$
- ▶ $\text{Ext}(f) = \{x \mid x \sqsubseteq f(x)\}$ and
- ▶ $\text{Fix}(f) = \text{Red}(f) \cap \text{Ext}(f)$.





- ▶ Start from \perp so that we obtain the **least** fixed point.
- ▶ Another possibility is to start in \top and move down. Whenever we stop, we are safe.
- ▶ But....no guarantee that we reach **lfp**





- ▶ Widening: replace \sqcup with a **widening operator** ∇ (nabla).
- ▶ ∇ is an upper bound operator, but not least:
for all $l_1, l_2 \in L : l_1 \sqcup l_2 \sqsubseteq l_1 \nabla l_2$.
- ▶ The point: take larger steps in the lattice than is necessary.
- ▶ Not precise, but definitely sound.



- ▶ Consider a sequence

$$l_0, l_1, l_2, \dots$$

- ▶ Note: any sequence will do.
- ▶ Under conditions, it becomes an **ascending** chain

$$l_0 \sqsubseteq l_0 \nabla l_1 \sqsubseteq (l_0 \nabla l_1) \nabla l_2 \sqsubseteq \dots$$

- ▶ that is guaranteed to stabilize.
- ▶ Stabilization point is known to be a reductive point,
 - ▶ I.e. a sound solution to the constraints



- ▶ Consider a sequence

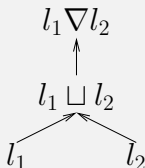
$$l_0, l_1, l_2, \dots$$

- ▶ Note: any sequence will do.
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$$l_0 \sqsubseteq l_0 \nabla l_1 \sqsubseteq (l_0 \nabla l_1) \nabla l_2 \sqsubseteq \dots$$

- ▶ that is guaranteed to stabilize.
- ▶ Stabilization point is known to be a reductive point,
 - ▶ I.e. a sound solution to the constraints
- ▶ but is not always a fixed point. Bummer.





- ▶ Let a lattice L be given and ∇ a widening operator, i.e.,
 - ▶ for all $l_1, l_2 \in L$: $l_1 \sqsubseteq l_1 \nabla l_2 \sqsupseteq l_2$, and
 - ▶ for all ascending chains (l_i) , the ascending chain $l_0, l_0 \nabla l_1, (l_0 \nabla l_1) \nabla l_2, \dots$ eventually stabilizes.
- ▶ The latter seems a rather selffulfilling property.



- ▶ How can we use ∇ to find a reductive point of a function?

$$\text{▶ } f_{\nabla}^n = \begin{cases} \perp & \text{if } n = 0 \\ f_{\nabla}^{n-1} & \text{if } n > 0 \wedge f(f_{\nabla}^{n-1}) \sqsubseteq f_{\nabla}^{n-1} \\ f_{\nabla}^{n-1} \nabla f(f_{\nabla}^{n-1}) & \text{otherwise} \end{cases}$$

- ▶ First argument represents all previous iterations, second represents result of new iteration.



- ▶ Define ∇_C to be the following upper bound operator:
 $[i_1, j_1] \nabla_C [i_2, j_2] = [\text{LB}_C(i_1, i_2), \text{UB}_C(j_1, j_2)]$ where
 - ▶ $\text{LB}_C(i_1, i_2) = i_1$ if $i_1 \leq i_2$, otherwise
 - ▶ $\text{LB}_C(i_1, i_2) = k$ where $k = \max\{x \mid x \in C, x \leq i_2\}$ if $i_2 < i_1$



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 - ▶ And similar for UB_C .
 - ▶ Exception: $\perp \nabla_C I = I = I \nabla_C \perp$.
- ▶ Essentially, only the boundaries of the first argument interval, values from C , and $-\infty$ and ∞ are allowed as boundaries of the result.
- ▶ Let $C = \{3, 5, 100\}$. Then
 - ▶ $[0, 2] \nabla_C [0, 1] = [0, 2]$
 - ▶ $[0, 2] \nabla_C [-1, 2] = [-\infty, 2]$
 - ▶ $[0, 2] \nabla_C [1, 14] = [0, 100]$



- ▶ Intuition by example.
- ▶ Consider the chain $[0, 1] \subseteq [0, 2] \subseteq [0, 3] \subseteq [0, 4] \dots$ and choose $C = \{3, 5\}$.
- ▶ From it we obtain the stabilizing chain:

$$\begin{aligned} & [0, 1], \\ [0, 1] \nabla_C [0, 2] &= [0, 3], \\ [0, 3] \nabla_C [0, 3] &= [0, 3], \\ [0, 3] \nabla_C [0, 4] &= [0, 5], \\ [0, 5] \nabla_C [0, 5] &= [0, 5], \\ [0, 5] \nabla_C [0, 6] &= [0, \infty], \\ [0, \infty] \nabla_C [0, 7] &= [0, \infty], \dots \end{aligned}$$

- ▶ Essentially, we fold ∇_C over the sequence.



- ▶ Recall the program

```
[x := 0]1
while [x >= 0]2 do
  [x := x + 1]3;
```

- ▶ Iterating with ∇_C with $C = \{3, 5\}$ gives

$A_o(1)$	\perp	\perp	\perp	\perp	\perp	\perp
$A_\bullet(1)$	\perp	$[0, 0]$	$[0, 0]$	$[0, 0]$	$[0, 0]$	$[0, 0]$
$A_o(2)$	\perp	$[0, 0]$	$[0, 0] \nabla_C [1, 1] = [0, 3]$	$[0, 5]$	$[0, \infty]$	$[0, \infty]$
$A_\bullet(2)$	\perp	$[0, 0]$	$[0, 3]$	$[0, 5]$	$[0, \infty]$	$[0, \infty]$
$A_o(3)$	\perp	$[0, 0]$	$[0, 3]$	$[0, 5]$	$[0, \infty]$	$[0, \infty]$
$A_\bullet(3)$	\perp	$[1, 1]$	$[1, 4]$	$[1, 6]$	$[1, \infty]$	$[1, \infty]$

- ▶ Note: not all interval boundaries are values from C



- ▶ Widening operator ∇ replaces join \sqcup :
 - ▶ Bigger leaps in lattice guarantee stabilisation.
 - ▶ guarantees reductive point, not necessarily a fixed point
- ▶ Widening operator: verify the two properties.
- ▶ Any complete lattice supports a range of widening operators. Balance cost and coarseness.
- ▶ Widening operator often a-symmetric: the first operand is treated more respectfully.
- ▶ Widening usually parameterized by information from the program:
 - ▶ C is the set of constants occurring in the program.
- ▶ We visit a finite, program dependent part of the lattice.

